

7.3 Configuring the controller using MULTIPLEX LAUNCHER

GB The simplest and most convenient method of configuring the ROXXY Smart Control is to use MULTIPLEX Launcher.

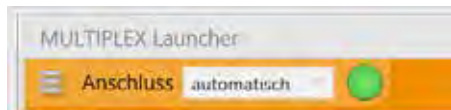


Launcher can be found in the Download area at www.multiplex-rc.de. You will also need the MULTIPLEX USB lead (Order No.: #85149).

Caution!
Observe the Chapter entitled “Safety notes”.

Preparation:

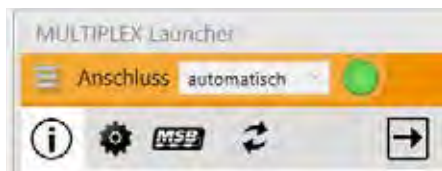
- Ensure that your model is securely restrained. Remove the propeller (aircraft / boat) or rotor blades, to eliminate the danger of damage or injury if the motor should burst into life unexpectedly.
- Locate the three-core servo lead connected to the Throttle channel at the receiver, and disconnect it.
- Locate the two-core MSB bus / telemetry data lead connected to the receiver, disconnect it, then re-connect it to the USB PC lead. If you wish, you can use the Y-lead which is included with the USB lead.
- Now start MULTIPLEX Launcher.








- Connect the flight / drive battery to the ROXXY Smart Control. If the program fails to detect the controller automatically, select the correct port manually in the COM-Port field.

Once the controller has been detected correctly, the screen displays the current information regarding software and hardware. You can now click on the symbols in the menu bar, after the various settings, and save the data.

Key to the symbols in the menu bar:



-  General information
-  Control settings
-  Telemetry settings
-  Firmware update
-  Adopt changes

After each change the arrow symbol starts to flash orange. Click on the setting to save the data to the speed controller.

Once you have entered and saved all the changes required, you can close MULTIPLEX Launcher and disconnect the battery from the speed controller.

The ROXXY Smart Control is now ready for use with the new settings.